

### Empower R2R Controller Design and Implementation with Data Analytics

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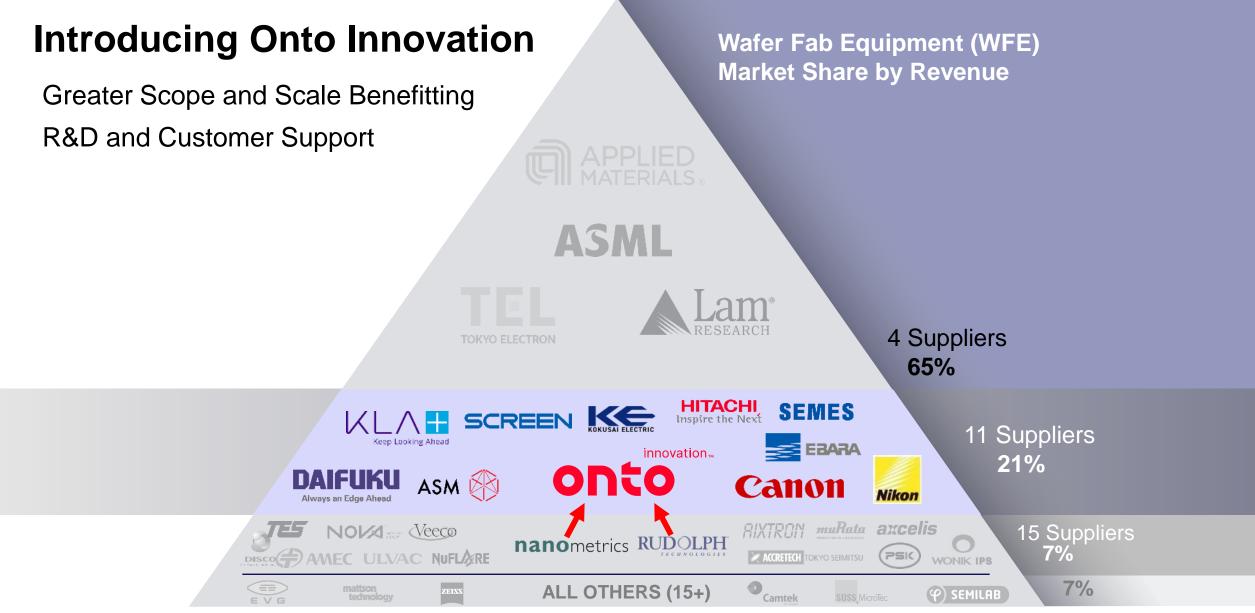
**APCSM Conference** 



### Outline

- Introduction to Onto Innovation
- R2R control overview
  - Threaded control vs. Non-threaded control
- CVD process R2R case study
  - Use of data analytics to facilitate controller design and implementation
- Conclusion

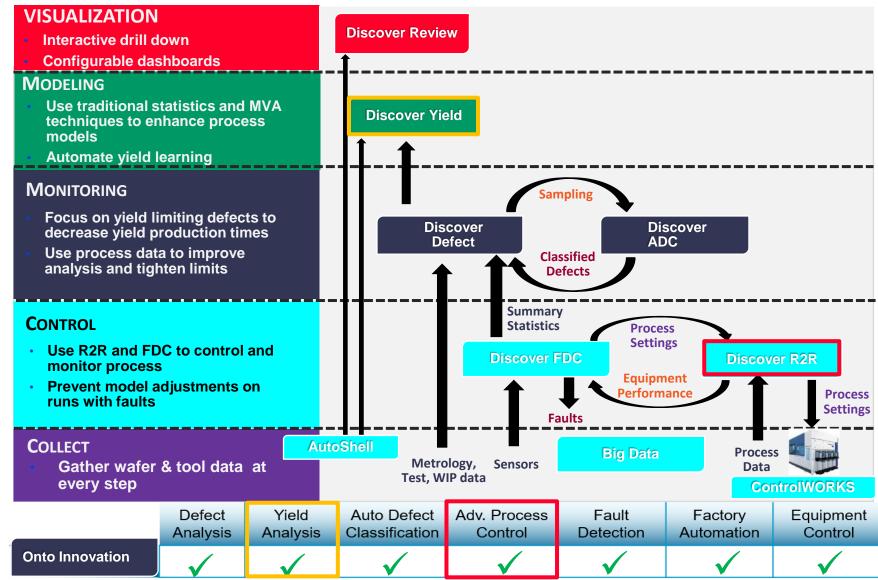




Source: Company Rank Order based on 2018 Share of Total WFE Revenue, Gartner Market Share Data, May 2019

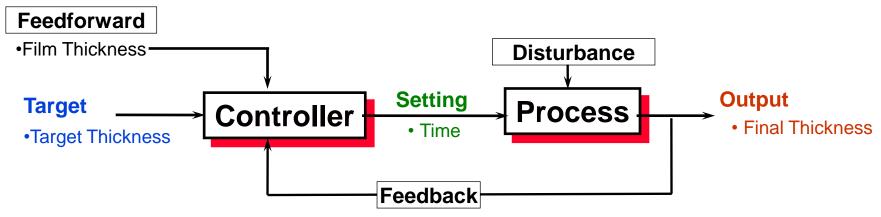


### **Onto Innovation Software Solutions**





### **Run-to-Run Control**

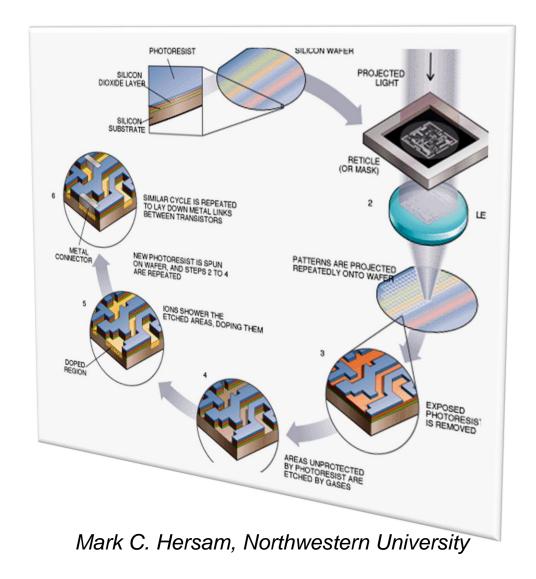


- Feedforward Control (Open-Loop Control)
  - A disturbance is measured, and the measurement is used to decide how to adjust a setting to keep output on target
  - No output measurement, cannot account for unmeasured disturbances
- Feedback Control (Closed-Loop Control)
  - An output is measured and the measurement is used to decide how to adjust a setting to keep output on target
  - Don't need to know disturbances, so don't measure them



### How Run-to-Run Control Can Help

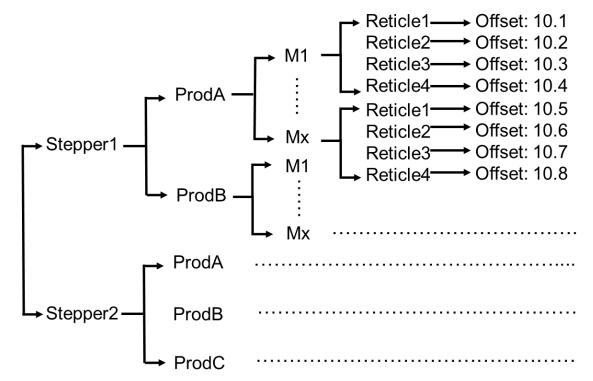
- Drive processes to target
  - Achieve proper film thickness, uniformity, stress, CD, overlay
  - Increase process capability (Cp&Cpk) and yield
- Reduce OoC/OoS, rework, pilot & monitor runs,
  - Increase tool up time
  - Increase throughput and reduce cycle time
- Allow tools to run longer between PM
  - Increase time between replacements
  - Reduce consumables
- Make adjustments automatically
  - Reduce engineering time
  - Eliminate human error





### **Partitions (Threads)**

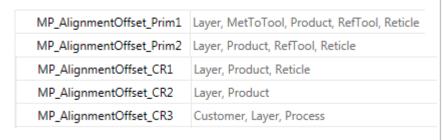
- Unique combinations of manufacturing context attributes, e.g., machine, product, layer, etc.
- Each partition has individual control loop using data only from itself.
- Proper definition of partitions separates disturbances into different groups (partitions) so that variability within each partition should be much smaller than the overall variability.
- Over-definition of partitions may undermine controller performance and lead to large number of partitions and data poverty.





# **High-Mix Challenges and Solutions**

- Hard to keep low-running products updated if they require their own partition
  - Track time and number of wafers/runs since partition was last tuned
    - Control-oriented dispatching to help ensure partition state will be updated (e.g., Anderson and Hanish, IEEE Trans. Semicond. Manuf., 2008)
    - Require send-ahead/pilot if last tuning was long ago (e.g., Krumanocker and Yelverton, APC Conference, 2015)
  - Similar partitions (e.g., reticles) can be combined into a partition group that share data with each other
  - Controller flexible enough to allow partition criteria change
  - Hierarchical partition definitions (e.g., Yelverton and Agrawal, SPIE, 2014; Sun, APC Conference, 2017)



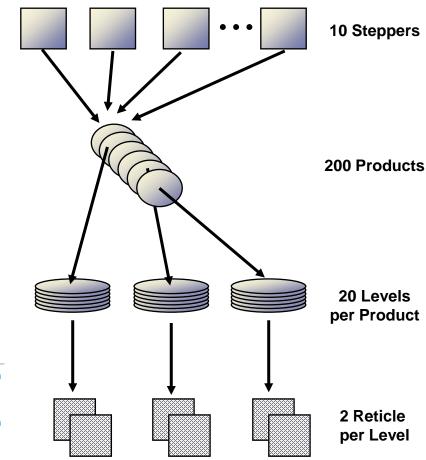
if(timeSinceLastTune(MP\_AlignmentOffset\_Prim1)<(3600\*24\*180)) then (MP\_AlignmentOffset\_Prim1) else(

if(timeSinceLastTune(MP\_AlignmentOffset\_Prim2)<(3600\*24\*180)) then (MP\_AlignmentOffset\_Prim2) else(

if(timeSinceLastTune(MP\_AlignmentOffset\_CR1)<(3600\*24\*180)) then (MP\_AlignmentOffset\_CR1) else(

if(timeSinceLastTune(MP\_AlignmentOffset\_CR2)<(3600\*24\*180)) then (MP\_AlignmentOffset\_CR2) else(

if(timeSinceLastTune(MP\_AlignmentOffset\_CR3)<(3600\*24\*180)) then (MP\_AlignmentOffset\_CR3) else(



### = 80,000 Interactions



C\_AlignmentSettingsTable)))))

### **Non-Threaded Control**

```
e.g., Wang et al, APC Conference, 2013
```

- Maintain state vector X(k) with an element for each independent context
- · Measured output predicted by linear combination of states based on context of run

 $y = [1 \ 0 \cdots 0 \ 1 \cdots 1 \ 0 \cdots] \cdot X + u = Tool1 + Layer2 + Product1 + u$ 

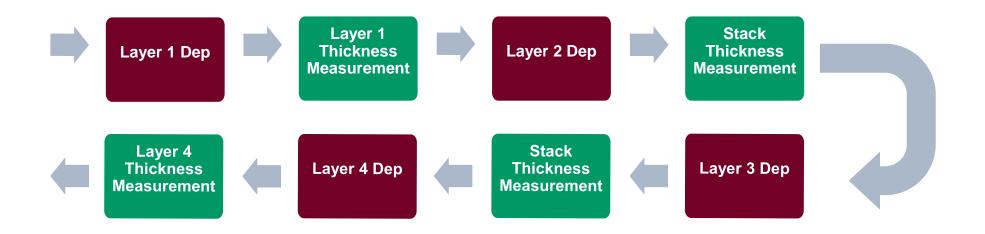
- Share information between partitions, therefore potentially less send-ahead/pilot wafers
  - Controller performance may deteriorate without frequent model update (e.g., Zou et al, APC Conference, 2014)
- Less straightforward implementation; not for strong non-linear interaction among states
  - Not practical for production use when numbers of states change
  - Threaded control works as well when noise is present

(e.g., Hanish, AEC/APC Symposium, 2005)



### **CVD Process Flow**

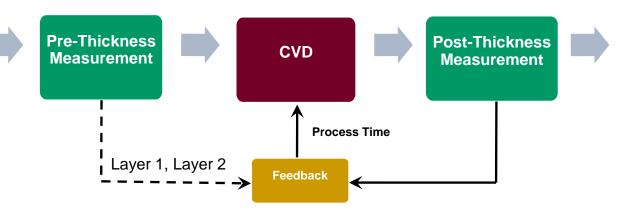
• R2R solution introduced for all product lines with about 14 product families and 4 layers to be controlled.

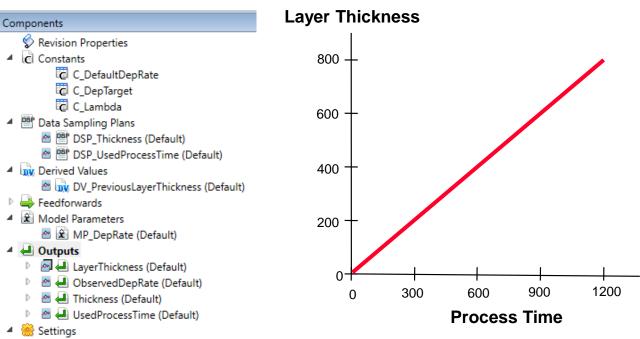




# **CVD Controller Design**

- Process model
  - LayerThickness = DepRate \* ProcessTime
- EWMA tuner
  - $PredDepRate(n+1) = (1-\lambda)*PredDepRate(n) + \lambda*ObservedDepRate(n)$
- Strategy components
  - Setting: ProcessTime
  - Model parameter: DepRate
  - Feedforward: PreThickness
  - Constant:  $\lambda$ , Thickness<sub>tgt</sub>, DefaultDepRate
  - DSP: DSP\_Thickness,
    DSP\_UsedProcessTime
  - Output: PostThickness<sub>avg</sub>, UsedProcessTime
  - Derived output: ObservedDepRate = (PostThk
    - PreThk) / UsedProcessTime





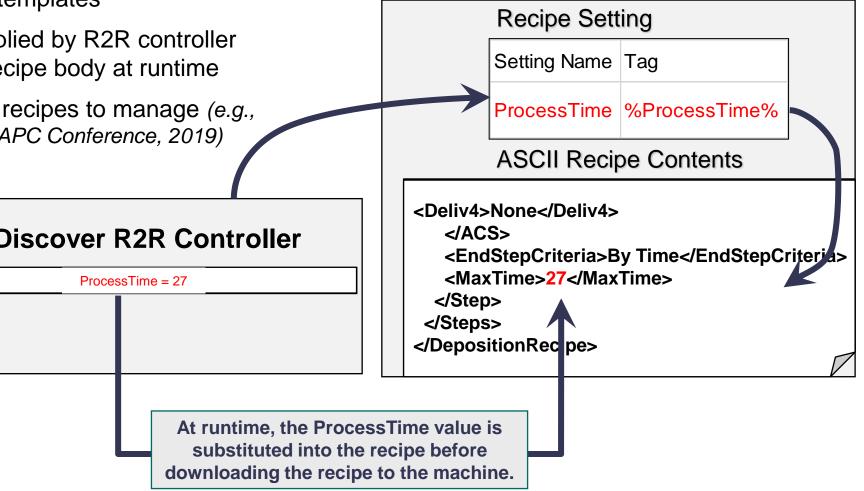


### **Total R2R/RMS Solution**

- Recipes stored as templates
- Setting values supplied by R2R controller and inserted into recipe body at runtime
- Reduce number of recipes to manage (e.g., Echevarria and Sun, APC Conference, 2019)

### **Discover R2R Controller**

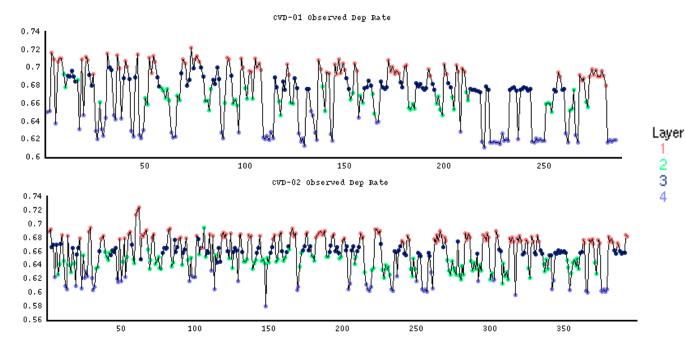
### **Discover R2R Recipe**

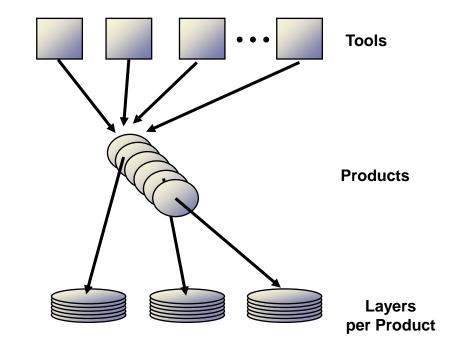




### **Dep Rate Partitioning**

- Separate disturbance into machine and material
  - Partition machine disturbance by machine
  - Partition material disturbance by product, layer, etc.
- Partition CVD controller by tool and layer at least
  - Observed dep rate is stratified by layer
  - Variability within each layer is much smaller than overall variability



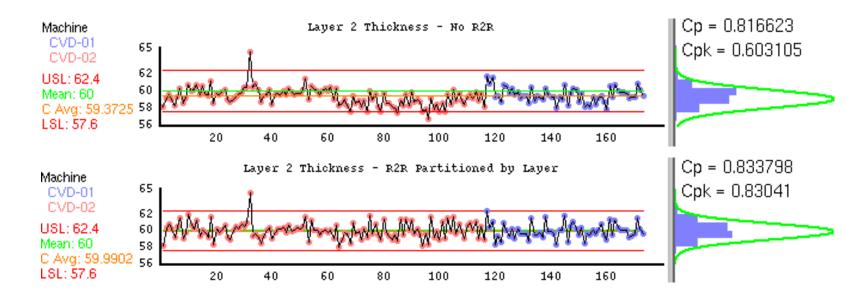




### **Results with Tool/Layer Partition**

- Simulated 679 runs on 2 tools and 4 layers within 2 months
- Results estimated significant reduction in thickness variability which corresponds to up to +38% increase in Cpk with optimized  $\lambda$
- Current thickness data is skewed too. R2R will drive it back to target

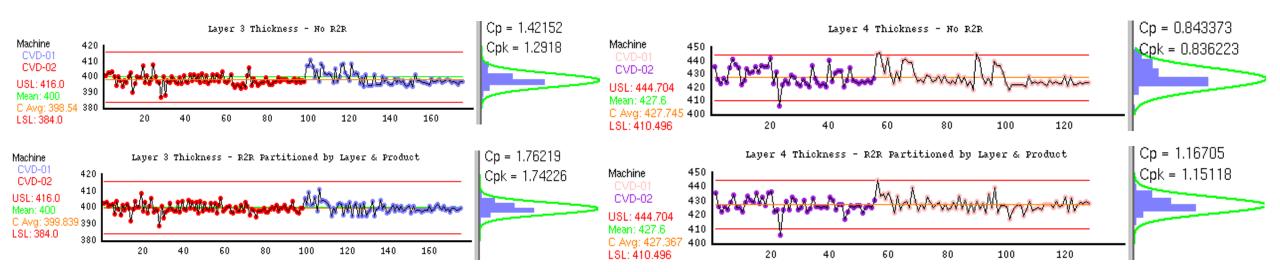
Layer	Cpk Increase	Optimal λ (CVD01, CVD02)
1	9%	0.2, 0.4
2	38%	0.3, 0.3
3	24%	0.3, 0.1
4	4%	0.5, 0.2



### **Results with Tool/Layer/Product Partition**

- Significant further Cpk improvement at Layer 3 & 4
- Controller performance deteriorates for Layer 1 & 2
- Process engineer raised concern about data starvation for low-running products

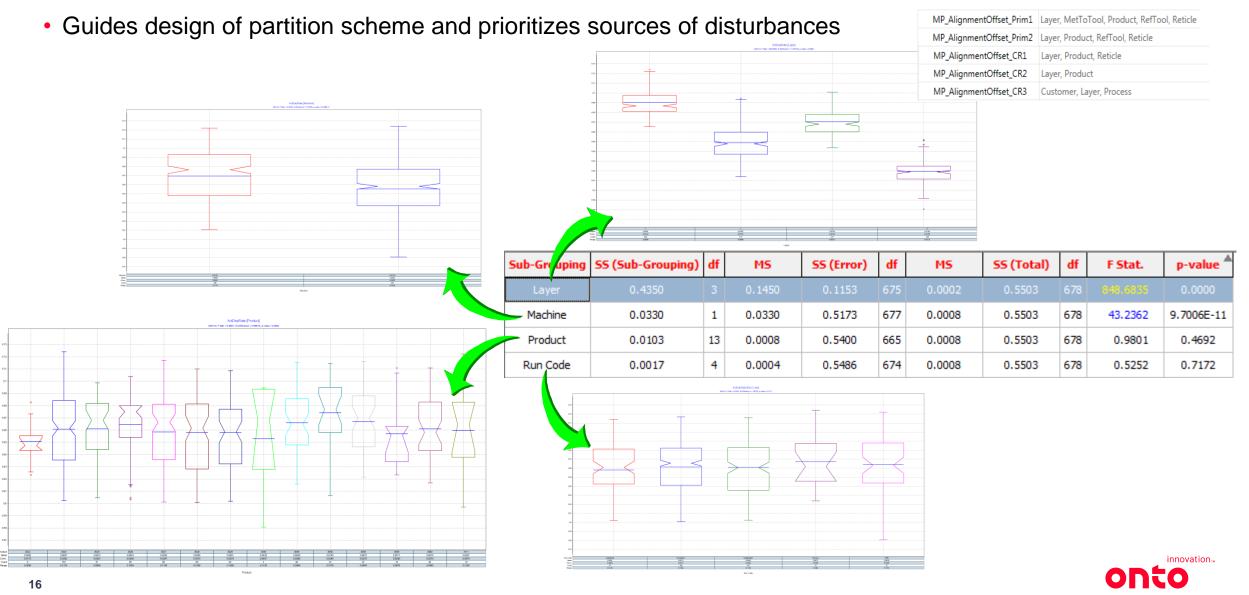
Layer	Cpk Increase	Optimal λ (CVD01, CVD02)
1	3%	0.5, 0.4
2	35%	0.2, 0.5
3	35%	0.5, 0.5
4	37%	0.7, 0.7





### **ANOVA for Dep Rate in Discover Yield**

• Verifies significant dep rate variability in Layer and Tool but less variability in Product



### Analyzing Dep Rate Offsets by Product

Machine=CVD-01, Layer=1

ANOVA: F Stat. = 2.5992, % Difference = 4.1847%, p-value = 0.006

0.6930 0.7058 0.7008

0.6964 0.7002 0.6993 0.6976

0.6604 0.6623 0.6604 0.6588 0.6436 0.6637

0.0035 0.0042 0.0024 0.0042 0.0047 0.0017 0.0000 0.0028 0.0015 0.0022 0.0019 0.0028 0.0021

0.0128 0.0110 0.0070 0.0114 0.0138 0.0056 0.0000 0.0078 0.0030 0.0060 0.0034 0.0076

Product

0.6

0.6

0.6

0.73

0.2

0.6

0.6

0.6

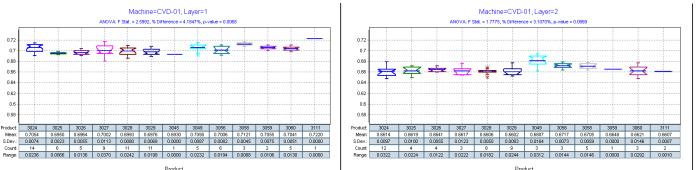
0.6

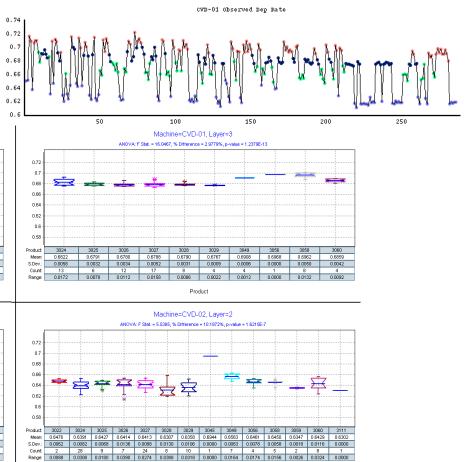
0.6

0.6

0.6

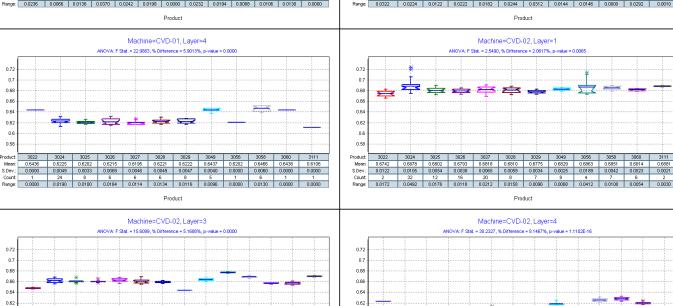
• Dep rate variability in Product not significant suggests controller remain partitioned by tool/layer to quickly capture trend but dep rate offset can be applied to achieve better control between products





Produc





0. 0.5

Product

S Dev

0.6048 0.6046 0.6040 0.6055 0.6055 0.6047 0.5806 0.6180 0.6064 0.6250 0.6271

0.0000 0.0025 0.0000 0.0008 0.0032 0.0044 0.0044 0.0000 0.0032 0.0000 0.0038 0.0066 0.0027

0.0062 0.0000 0.0012 0.0108 0.0128 0.0080 0.0000 0.0086 0.0000 0.0090 0.0094

Product

### **Modified Controller Design**

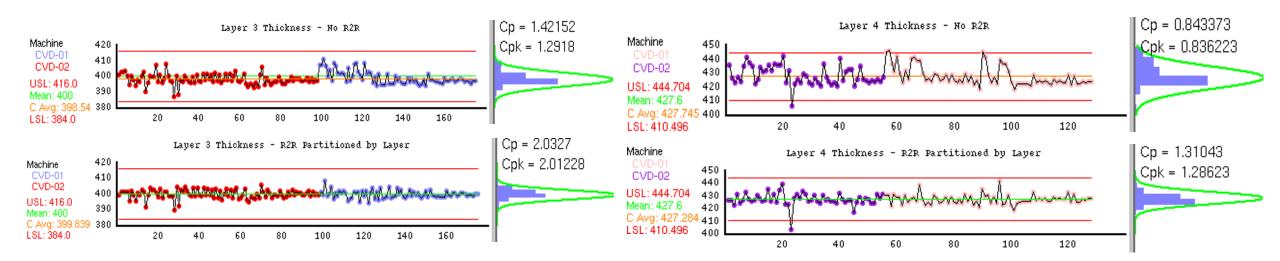
- Process model
  - LayerThk = (DepRate<sub>tool/layer</sub> + Offset<sub>tool/layer/product</sub>) \* ProcessTime
- EWMA tuner
  - $PredDepRate(n+1) = (1-\lambda) * PredDepRate(n) + \lambda * (ObservedDepRate(n) Offset)$
- Sample dep rate offset from YMS

	Indexing			
Name 🍸	Layer 🍸	Machine 🍸	Product 🍸	Value 🍸
C_DepRateOffset	×	×	×	0
C_DepRateOffset	2	CVD-01	3049	0.016
C_DepRateOffset	2	CVD-01	3056	0.008
C_DepRateOffset	2	CVD-01	3058	0.006
C_DepRateOffset	3	CVD-01	3049	0.008
C_DepRateOffset	3	CVD-01	3058	0.014
C_DepRateOffset	4	CVD-01	3049	0.018
C_DepRateOffset	4	CVD-01	3058	0.02
C_DepRateOffset	2	CVD-02	3028	-0.012
C_DepRateOffset	2	CVD-02	3029	-0.006
C_DepRateOffset	2	CVD-02	3049	0.014
C_DepRateOffset	3	CVD-02	3056	0.014
C_DepRateOffset	3	CVD-02	3058	0.006
C_DepRateOffset	4	CVD-02	3024	-0.008
C_DepRateOffset	4	CVD-02	3027	-0.006
C_DepRateOffset	4	CVD-02	3028	-0.006
C_DepRateOffset	4	CVD-02	3049	0.006
C_DepRateOffset	4	CVD-02	3058	0.012
C_DepRateOffset	4	CVD-02	3060	0.008

### **Results with Modified Control Model**

- Significant further improvement for Layer 2, 3 & 4 even comparing to partition by tool/layer/product
- Handles low-running products better

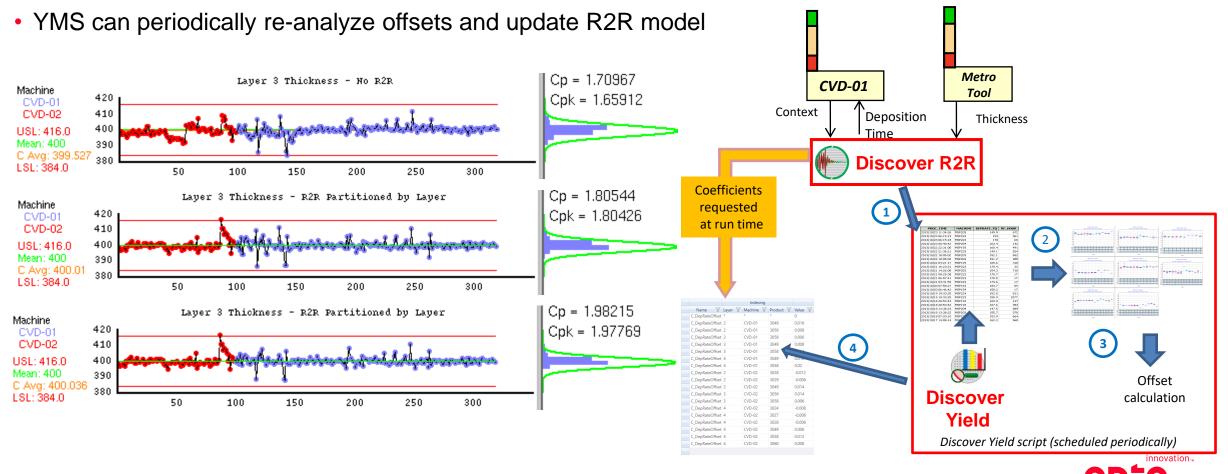
Layer	Cpk Increase	Optimal λ (CVD01, CVD02)
1	9%	0.2, 0.4
2	48%	0.2, 0.2
3	56%	0.2, 0.2
4	54%	0.2, 0.2





### **Frequent Offset Update Maintains Controller Performance**

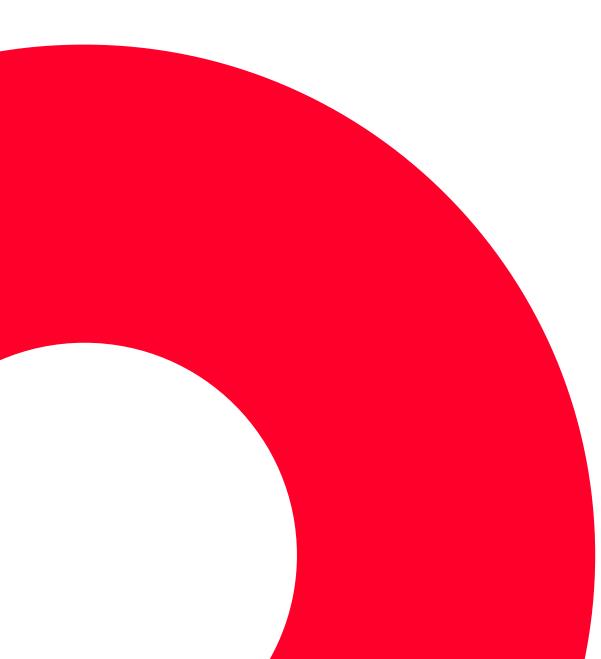
- Simulated modified control model with new production data
- Controller performance deteriorates as old products phased out and new products coming in
- Obtaining new dep rate offsets by product helps maintain controller performance



### Summary

• Traditionally, R2R controllers handle disturbances with partitions/control threads

- Data analytics can be employed to
  - Guide design of partition scheme and prioritize sources of disturbances
  - Improve control model with offsets within partition to achieve better control
  - Re-analyze offsets periodically to help maintain controller performance
- Results from CVD process showed significant Cpk improvements



# **Thank You**

谢谢   謝謝	ありがとう	Obrigado
Danke	감사합니다	Merci

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